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## Martian Moon Sample Return (MMSR) An ESA mission study

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## **Programmatic framework**



#### Mars Robotic Exploration Programme (MREP) – part of the ESA/NASA Joint Mars Exploration Programme (JPEP)

- Aim: return samples from Mars in the 2020s
- Initially spanned several launch opportunities including rovers and orbiters
  - 2016 ExoMars Trace Gas Orbiter (TGO) + ESA Entry, Descent, and Landing **Demonstrator Module**
  - 2018 ESA/NASA rover sample caching mission
- 2018 mission currently under feasibility assessment •
- To be prepared for >2018: ESA initiated further mission studies •
- COX COCUMENT Design A SINT Martian Moon Sample Return (MMSR): upcoming CDF study + past studies
  - Network Lander: upcoming CDF study + past studies
  - Mars precision landing: ongoing industry studies Ē
  - Mars Sample Return orbiter: ongoing industry studies Ē
  - And previously studied:
  - Atmospheric sample return: CDF study

#### Goal of current study

Bring the candidate missions to a level of definition enabling their programmatic evaluation, including development schedule and Cost at Completion to ESA.

### **Programmatic framework**



#### The Science Definition Team was asked to

- (a) Describe the science case for such a mission
- (b) Propose a baseline mission scenario or concept
- (c) Propose the baseline science instrumentation

#### Constraints:

- Sample return mission to either Phobos or Deimos
- Launch with Soyuz
- 'ESA affordable' (but can have collaboration), Cost at Completion <~750 800 MEuro
- Extensive reuse of existing studies

## **Timetable**



Mars future missions: 2011/2012 timetable and key events	
Event	Date
Setting of Science Definition Teams for supporting the Mission definition for the Mars network mission and Mars moon sample return missions	April 2011
SDTs reports on Mars network and Martian Moon Sample Return missions	July 2011
Completion of ESA internal studies (CDF) for the mission definition	November 2011
Completion of industrial studies on MSR Orbiter and Mars Precision Lander missions	December 2011
Programmatic consolidation	December 2011 - January 2012
Presentation to PB-HME (Programme Board)	February 2012
Elaboration of international collaboration schemes	January – June 2012
PB-HME decision on way forward for C- Min(2012)	June 2012

## Science goals - 1



#### **Top-level science goal:**

Understand the formation of the Martian moons Phobos and Deimos and put constraints on the evolution of the solar system.

- Constrain the moon formation scenario by analysing returned samples
- Constrain dynamical models of the early solar system by showing how often a large impact occurs

### Science goals - 2



- (a) co-formation with Mars (see e.g. Burns 1992 and references therein);
- (b) capture of objects coming close to Mars (Bursa et al., 1990);
- (c) Impact of a large body onto Mars and formation from the impact ejecta (Singer 2007, Craddock 2011).



## Science goals – 3



#### Returned sample will allow:

- Detailed chemical analysis (much more than in-situ), mineralogy, texture...
- Dating

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#### $\Rightarrow$ Better constrain formation mechanism

e.g.: Martian material? Asteroidal material?



### **Phobos or Deimos?**



#### Phobos-Grunt => go to Deimos? Thomas et al. (1996): 200 m regolith, "…from the ejecta being accreted … long after the impact…"

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Go to Phobos, but to a different geological unit (still to be discussed)

Preliminary mission analysis result: Deimos would allow 60 – 100 kg more s/c mass



Image credit: NPO Lavochkin



From Thomas 2011

*MMSR-RSSD-HO-001/1.0* 16 Jun 2011

#### HiRISE image PSP\_007769\_0910, unsharp masked (Thomas 2011)



### **Mission building blocks**



### Could build on Marco Polo's design...



### **Deimos Sample Return**





MMSR-RSSD-HO-001/1.0 16 Jun 2011



#### **Baseline payload**

Again we use the Marco Polo study as a starting point:

- Wide angle camera
- Narrow angle camera
- Close-up camera
- Vis/NIR imaging spectrometer (0.4–3.3 µm)
- MIR spectrometer (5–25 µm)
- Radio science

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More to be discussed, depends on available mass

	Total
Mass [kg]	25
Power [W]	50
Data volume [Gbit]	280

Coloured image of Eros, Credit: NASA





## **Spacecraft configuration**



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### Marco Polo - Main spacecraft



Contractor 1: Corer, topmounted capsule, one articulated arm inside central cylinder







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**Contractor 2**: Corer, bottom-mounted capsule, two articulated arms

Contractor 3: Fast sampler, top-mounted capsule, transfer via landing pads/legs + elevator in central cone



#### SCIENCE **Marco Polo Earth Re-entry** Capsule Farachut 45° half-cone angle front shield econdary Structure and Electronics Connection for the Secondary Structure In-development lightweight ablative material or classical carbon phenolic Capsule mass: 25 – 69 kg Primary Structure **Front shield** Container Antenna Main parachute Beacons, batteries Back shield Location for Parachute equipments Location for Sample C/R low density crushable material container MMSR

### **Conclusion**



- ESA is studying a Martian Moon Sample Return mission ٠
- Phobos or Deimos? ٠
- Science case has been • defined
- Detailed science require-۲ ments are being iterated
- Mission scenario is being • developed
- ESA-internal 'CDF' study before end 2011
- Decision on further activities ۲ envisaged by PB-HME in Jun 2012

PB = Programme Board

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Credit: HiRISE, MRO, LPL (U. Arizona), NASA

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#### Additional slides





#### Why do we need to return samples?





## Superior instruments...

"Miranda" GC-IRMS Laboratory Isotope ratio ± 0.01%

> Rosetta Ptolemy In situ Isotope ratio ± 1%

In-situ instruments limited (mass/volume/power/reliability) MMSR-RSSD-HO-001/1.0 16 Jun 2011



# Superior instruments...





## **Superior instruments...**

### In-situ measurements provide insufficient precision





In-situ measurements provide little or no sample discrimination

100µm



### Complexity...

eesa

- Same sample analysed by many instruments
- Complex sample selection and preparation

